

Adding Remote Controller Functionality To Any Stereo

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Abstract: Use of stereo has become common in our lives. They are used in cars, TVs, music players etc. And it is essential at least to control their volumes. Suppose there is a stereo amplifier which functions pretty well but it does not have a remote. It would be very annoying if its volume cannot be controlled. So this project is useful as it creates a device which makes use of any existing remote to control the volume. For controlling the volume, we use a volume controller IC. The electronic volume controller IC PT2258 is a digital potentiometer which can be controlled using I2C protocols. It is used to control the attenuation for every combination possible from 0 to -79 dB/step. Universal IR receiver is used to decode the IR codes and the data will be transferred to the Arduino which in turn communicates with the IC PT2258 and controls the volume. The device also consists of two buttons, which are used to synchronize the IR code of the existing remote with the device. So the user will be able to use the device easily.

Keywords:

1. INTRODUCTION

The device designed is used to control the stereo which doesn't come up with a remote controller or a device which is so old that the remote controller is not available in the market. It will help the users to control the volume of any stereo with any remote they have got with them. So to be precise we can add up a remote controllable system to a normal computer speaker or any speaker that are readily available in the market which doesn't come with remote and we need to control the volume of the same using a remote controller.

The device makes use of an Arduino, IC PT2258 which is a digital potentiometer, Universal IR receiver, two switches and 4 audio jacks (2 for input and 2 for output). The Universal IR receiver receives the code and is given to the Arduino. Arduino takes the value and controls the IC PT2258. The volume is controlled by making attenuation in the channels. Thus the output of the device will be attenuated signal of the input.

The same device can also be made using a pulse detector and an analog potentiometer IC, but the problem is that, we need to provide a predefined remote controller along with the device. Else we have to redesign the pulse detector each time the user needs to use any different remote controllers. On using an Arduino, the predefined IR codes can be changed simply by pressing the switch in the device. By pressing the switch new IR values will be written to the device.

The main application of this device is that in a stereo, which does not come with any remote or whose remote is lost or damaged but they work fine manually, can be controlled with any available remote

2. LITERATURE SURVEY

2.1 Humble Volume Control Circuit

The humble volume control circuit can use to control the volume. Volume controls are usually implemented with a potentiometer configured as a voltage divider. The signal goes to lug 1, the output is connected to the wiper (lug 2) and the lug 3 is connected to ground. If we turn the pot shaft, more or less of the signal voltage is sent to either to ground (quieter) or to the output through the wiper (louder). This simple approach works well, but we are concerned with stereo, which has that pesky concept of two independent channels. But your standard pot only is a "single-gang" device: it only has one set of lugs.

There are many issues with dual gang pots. Potentiometers are not exact devices. Their tolerance ratings aren't terribly high, usually in the range of 10percentage–20percentage. That means that you can grab two 10K ohm pots of the exact same part and manufacturer and expect one pot to max out at 8k and the other at 12k. This really isn't a big deal for most applications circuits are designed with part tolerances in mind.

Stereo input volume control with those variances. Each "gang" of the pot could be off by as much as 20 percentages, and matching of both gangs with a given shaft position could be way off also, Make sense in an empirical way. The result is that by using a cheap dual-gang pot as a volume control you are actually building in an unintentional balance control also. You can never really be sure if the left and right levels being reproduced are what they were when recorded. The problem is these variances can become quite pronounced when you are dealing a stereo volume control. But in our project attenuation is properly controlled by IC PT228 by different attenuation steps so that balance control problem is minor

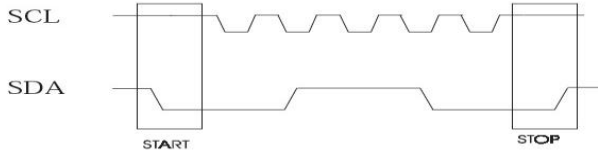


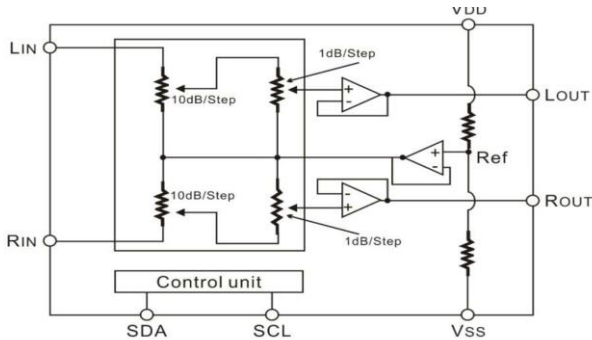
Figure 3: Start and Stop Condition Diagram

STOP CONDITION

The Stop Condition is activated when, SCL is set to HIGH and SDA shifts from LOW to HIGH State. Every byte transmitted to the SDA Line consists of 8 bits.

SOFTWARE DESCRIPTION

PT2258 Address Code depends on the state of CODE1 (Pin No. 17) and CODE2 (Pin No.4). If CODE1 or CODE2 is connected to Vcc, then CODE1 or CODE2 is set



to 1. If CODE1 or CODE2 is connected to the Ground, it is set to 0. Data byte Description. Every byte transmitted to SDA line consist of 8 bits. Each byte must be followed by acknowledge bit. The MSB is transmitted first.

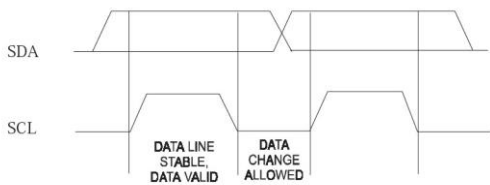


Figure 3: Start and Stop Condition Diagram

FUNCTIONAL DESCRIPTION

Data are transmitted to and from the microprocessor to the PT2258 via the SDA and SCL. The SDA and SCL make up the BUS Interface. A data on the SDA Line is considered valid and stable only when the SCL Signal is in

HIGH State. The HIGH and LOW States of the SDA Line can only change when the SCL signal is LOW.

INTERFACE PROTOCOL

- A start Condition
- A chip Address Byte including PT2258 address. 8th bit of the byte must be 0. It must always acknowledge the end transmitted byte.
- Data sequence (N-bytes+Acknowledge)

○ **IR Sensor**

IR used in this device is a universal IR receiver. Universal IR receiver is used to read the infra-red code. It converts the infra-red code to digital signal a transmits it through the digital pin to the micro-controller or microprocessor.

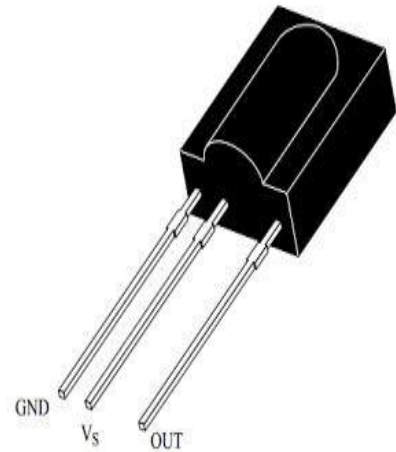


Figure 6: Pin Out of IR Sensor

| M SB | | | | | | | LS B | |
|---------|---|---|---|----|----|---|---------|--|
| 1 | 1 | 1 | 0 | A3 | A2 | A | A0 | 6-Channel- - 1dB/step |
| 1 | 1 | 0 | 1 | 0 | B2 | B | B0 | 6- channel- - 10dB/step |
| 0 | 0 | 0 | 1 | A3 | A2 | A | A0 | channel No.3- - 1dB/step |
| 0 | 0 | 0 | 0 | 0 | B2 | B | B0 | channel No.3- - 10dB/step |
| 0 | 0 | 1 | 1 | A3 | A2 | A | A0 | channel no.4- - 1dB/step |
| 0 | 0 | 1 | 0 | 0 | B2 | B | B0 | channel no.4- - 10dB/step |
| 0 | 1 | 0 | 1 | A3 | A2 | A | A0 | channel No.2- - 1dB/step |
| 0 | 1 | 0 | 0 | 0 | B2 | B | B0 | channel No.2- - 10dB/step |
| 0 | 1 | 1 | 1 | A3 | A2 | A | A0 | channel No.5- - 1dB/step |
| 0 | 1 | 1 | 0 | 0 | B2 | B | B0 | channel No.5- - 10dB/decade |
| 1 | 0 | 0 | 1 | A3 | A2 | A | A0 | channel No.1- - 1dB/step |
| 1 | 0 | 0 | 0 | 0 | B2 | B | B0 | channel No.1- - 10dB/step |
| 1 | 0 | 1 | 1 | A3 | A2 | A | A0 | channel No.6- - 1dB/step |
| 1 | 0 | 1 | 0 | 0 | B2 | B | B0 | channel No.6- - 10dB/step |
| 1 | 1 | 1 | 1 | 1 | 0 | 0 | M | 6-Channel, M=1 MUTE ON, M=0 MUTE OFF |

ATTENUATION UNIT BIT

| A3/... | A2/B2 | A1/B1 | A0/B0 | ATTENUATION VALUE(dB)+ |
|--------|-------|-------|-------|---------------------------|
| 0 | 0 | 0 | 0 | 0/0 |
| 0 | 0 | 0 | 1 | -1/-10 |
| 0 | 0 | 1 | 0 | -2/-20 |
| 0 | 0 | 1 | 1 | -3/-30 |
| 0 | 1 | 0 | 0 | -4/-40 |
| 0 | 1 | 0 | 1 | -5/-50 |
| 0 | 1 | 1 | 0 | -6/-60 |
| 0 | 1 | 1 | 1 | -7/-70 |
| 1 | 0 | 0 | 0 | -8/... |
| 1 | 0 | 0 | 1 | -9/... |

Arduino and Programming

Algorithm

1. Start
2. Check the buttonstate1 and buttonstate2.If any one of them is high, save the IR code received as a and b respectively
3. Read the IR codes available at the IR sensor
4. Compare it with a and b.
5. If IR code received is a.
6. And if the attenuation factor is i is greater than 0,Then i = i -5,and jump to step 10
7. If IR code received is b
8. And if the attenuation factor is i is lesser than 79,Then i = i +5,and jump to step 10
9. If the IR code is not a and b, then ignore them.
10. Split the attenuation factor i to ones and tens.
11. Transmit this ones and tens to the PT2258 IC through I2C channels.
12. Jump to step2

Hardware Description

IC PT2258

PT2258 is a 6-Channel Electronic Volume Controller IC utilizing CMOS Technology specially designed for the new generation of AV Multi-Channel Audio System. PT2258 provides an I2 C Control Interface, an attenuation range of 0 to -79 dB at 1 dB/step, low noise, high channel separation. Housed in 20-pin, DIP or SO Package, PT2258's pin assignments and application circuit are optimized for easy PCB Layout and cost saving advantages.

The main features of IC PT2258 are as follows:

- CMOS Technology
- Low Power Consumption
- Least External Components
- Attenuation Range: 0 to -79 dB at 1dB/step
- Operating Voltage: 5 to 9v Low Noise, S/N Ratio>100dB (A-weighting)
- High Channel Separation
- I2 C Bus Control Interface
- Selectable Address
- 6-Channel Outputs

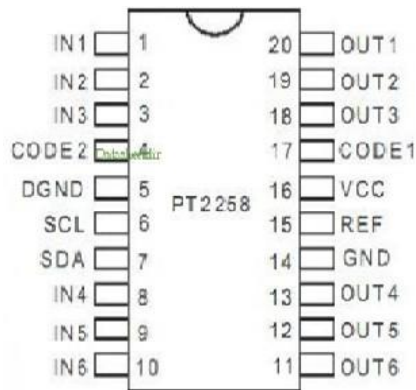


Figure 5.1: Pinout Diagram Of IC PT2258

IC PT2258 has any applications such as:

- AV Surround Audio Equipment
- Car Audio
- Mini Components
- Computer Multi-Media Speaker
- Other Audio Equipments

IR Sensor

An Infra red (IR) sensor is used to detect obstacles in front of the robot or to differentiate between colors depending on the configuration of the sensor. The picture shown is a very simple black box model of the IR Sensor. The sensor emits IR light and gives a signal when it detects the reflected light. It is a universal IR receiver which receives all the IR codes that comes to it and it consist of 3 pins. It is a universal IR receiver which receives all the IR codes that comes to it and it consist of 3 pins. Vcc, GND and digital out. Digital output gives the IR code received digitally. This is a simple infra red receiver which receives all the IR codes. It doesn't come specific. It is a universal one. It receives the IR code and transmit the received data digitally through out the digital pin.



Figure 5.2: Ir Sensor Block Diagram

RESULT

The device was designed and implemented. And the device works fine with almost all remote controllers available in the market.

4. CONCLUSION AND FUTURESCOPE

A device is designed and implemented in such a way that it can use any existing remote, to control the volume of a remote less stereo or can be used instead of a damaged remote. In this project we have studied how to control the volume using volume control IC, PT2258. Basic understanding about the IR sensor and Arduino was also studied during this work. The design and verification of the remote control device was successful. The main advantage of this device is that any available remote can be used to control the volume of the required stereo just by pressing the buttons on the device implemented. Thus it is useful to operate even an old, good functioning stereo as it helps to control the volume. The project gave practical knowledge about the electronic circuit and components used in this work and helped to develop new ideas with proper guidance and help of facilities from the department. Project got completed successfully. Circuit can have further implementation in the future.

5. REFERENCES

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